

# Quantum Walks & algorithms

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In part based on joint work with  
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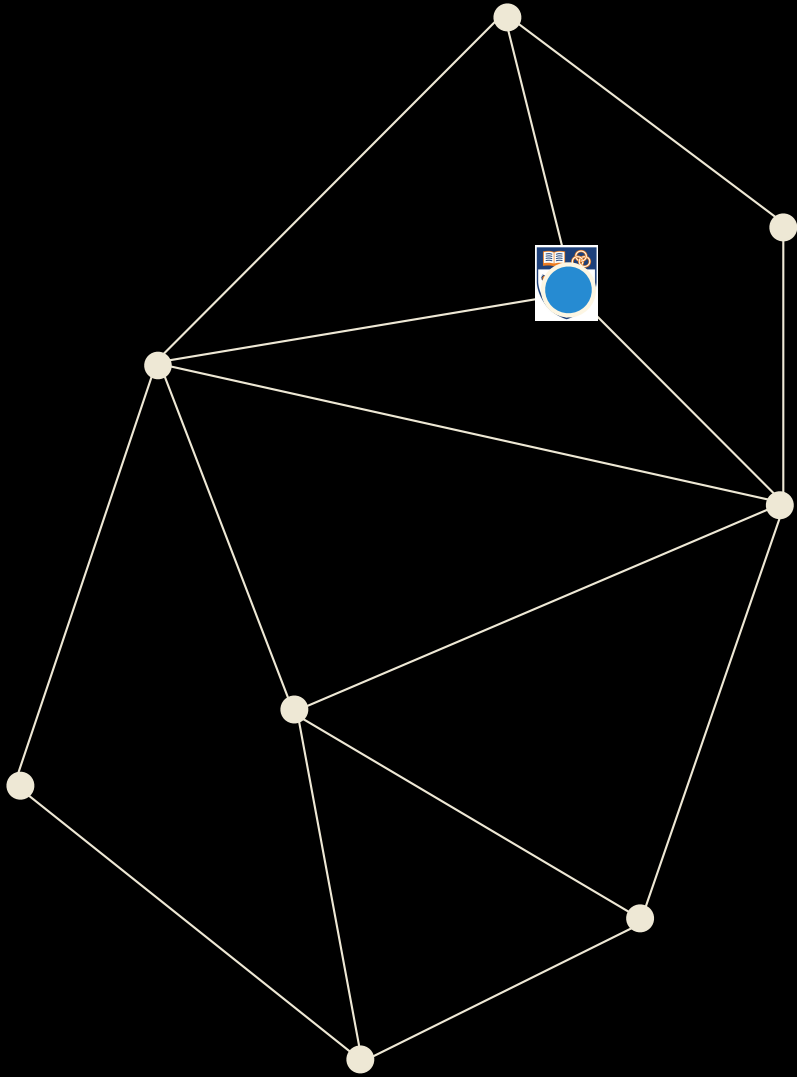
in arXiv:1612.08958,  
QIP 2017, STACS 2017, ICALP 2017

# Quantum algorithm

$$|\text{final}\rangle = (\mathbf{WG})^T |\text{init}\rangle$$



# Random walk



Setup walk at a random vertex

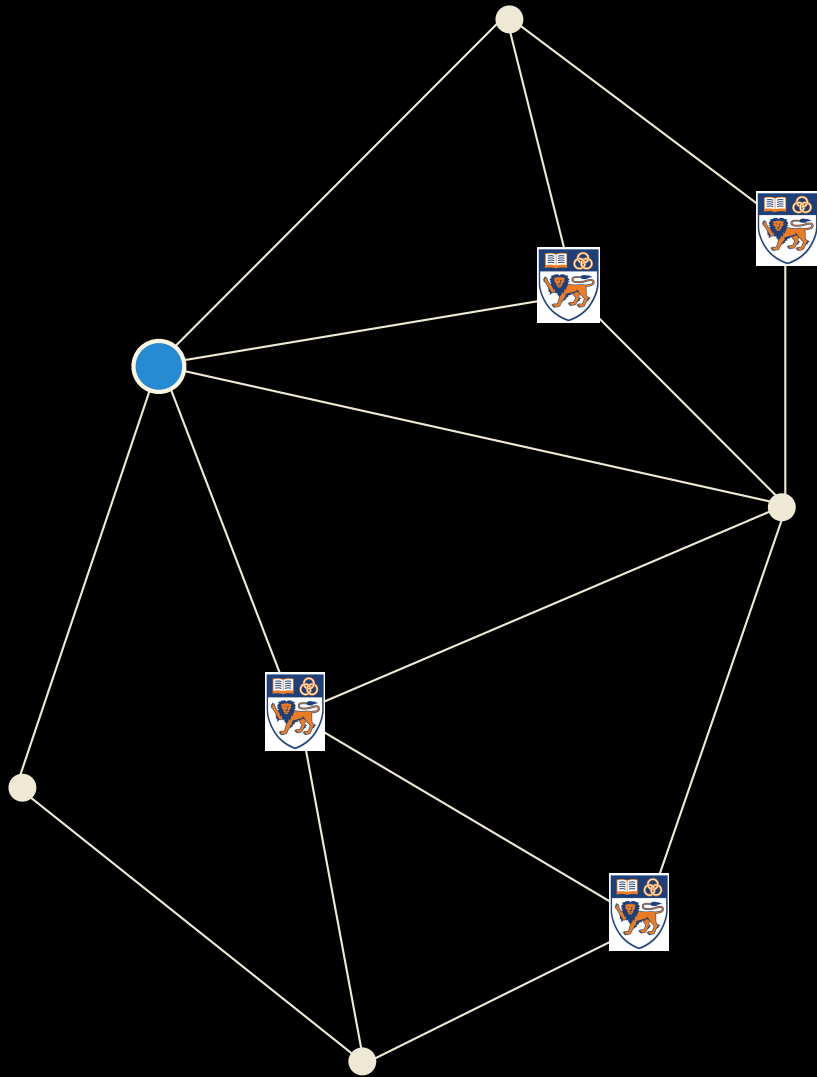
Repeat **T** times

- Check if vertex solution. If so, halt.
- Update by walking to a random neighbor

$T = \text{Hitting Time}(P, \text{AQIS})$

Cost =  $S + T(C + U)$

# Random walk



Setup walk at a random vertex

Repeat **T** times

- Check if vertex solution. If so, halt.
- Update by walking to a random neighbor

$T = \text{Hitting Time}(P, M)$

Cost =  $S + T(C + U)$

# Quantum Walk

Setup  $|\text{init}\rangle$

Repeat  $T_q$  times

- Check  $G$
- Update  $W$



$$\text{Cost} = S + T_{\text{quantum}}(C + U)$$

$$\text{Want: } T_{\text{quantum}} = \sqrt{T_{\text{classical}}}$$

# Checking query (**G**)

Goal: Find a marked  $g$



$$|x\rangle \mapsto \begin{cases} -|x\rangle & \text{if } x \text{ is marked} \\ |x\rangle & \text{otherwise} \end{cases}$$

We can ask questions of the form:  
“Is vertex  $x$  marked or not?”

$$\text{Ref}(g) = \text{Id} - 2|g\rangle\langle g|$$

$$\text{Ref}(g) = \text{Id} - 2 \sum_{g \text{ marked}} |g\rangle\langle g|$$

$\varepsilon = \text{Prob}[\text{random vertex is marked}]$

1 query to **G**  $\equiv$  1 checking cost

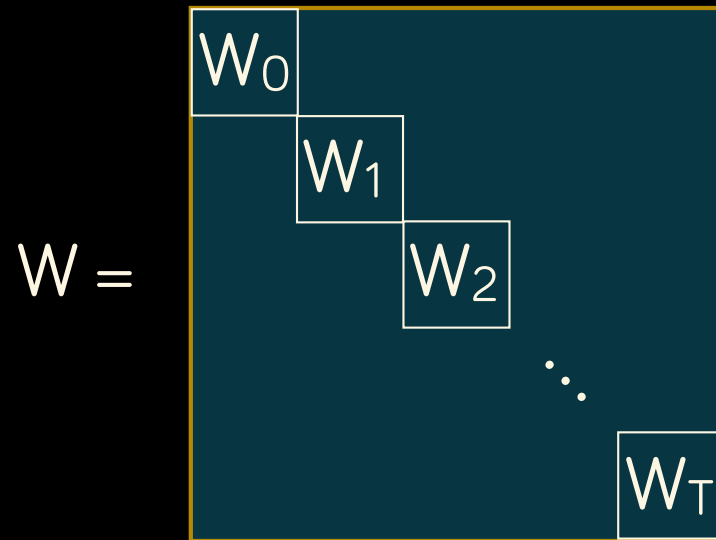
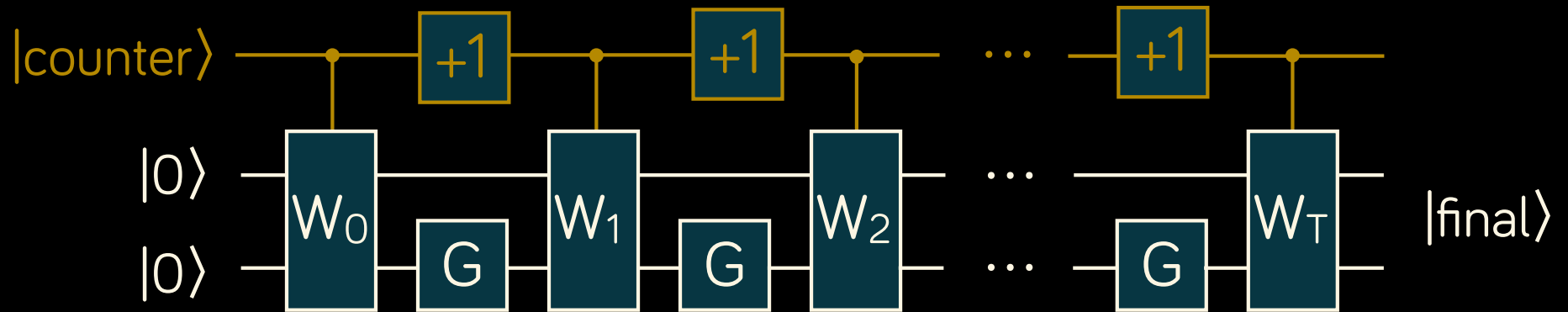
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$$|x\rangle \mapsto (-1)^{[x \text{ marked}]} |x\rangle$$

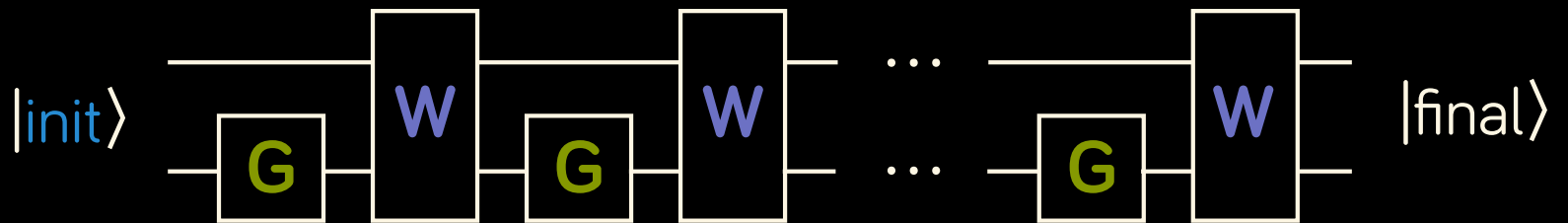
$$|x\rangle |b\rangle \mapsto |x\rangle |b \oplus [x \text{ marked}]\rangle$$

$$|x\rangle |b\rangle \mapsto (-1)^{b \cdot [x \text{ marked}]} |x\rangle |b\rangle$$

# Universal quantum algorithm



# Universal quantum algorithm



$$|final\rangle = (WG)^T |init\rangle$$

$$\text{Total Cost} = S + T(C + U)$$

**S** = Setup cost

**C** = Checking cost

**U** = Update cost

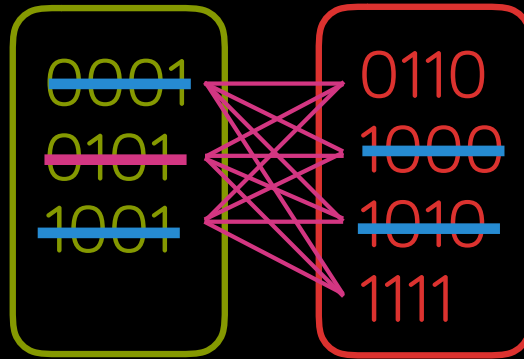


# A universal construction of $W$

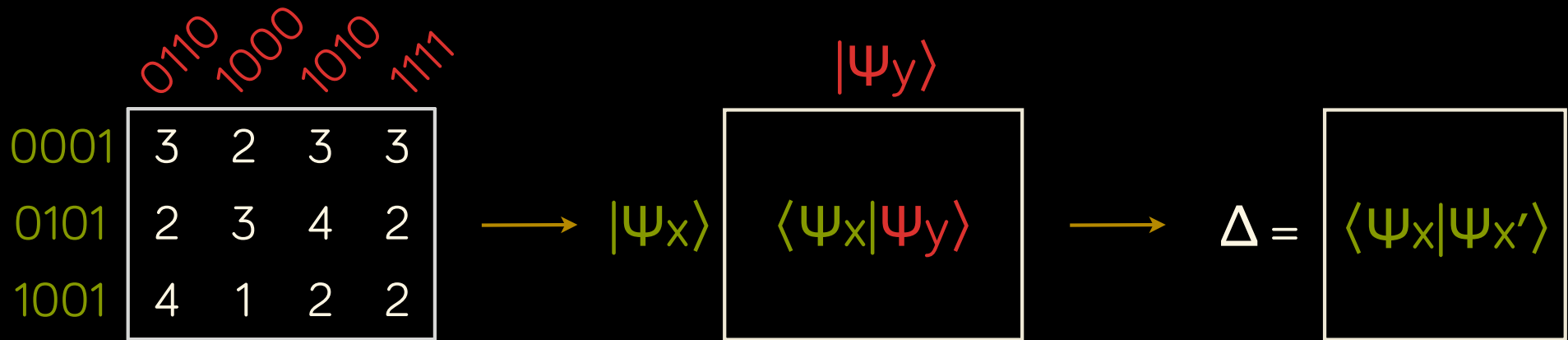
$$X = X_1 X_2 X_3 X_4$$

Query:  $X_2 = 1$

Query:  $X_3 = 1$



$$|\text{final}\rangle = (\mathbf{W}\mathbf{G})^T |\text{init}\rangle$$



$$\#\text{Queries} \geq \max_{\Gamma} \frac{\|\Gamma\|}{\max_i \|\Gamma_i\|}$$

$W$  = reflection about +1 eigenspace of  $\Delta$

# Four algorithms

$$|final\rangle = (\mathbf{WG})^T |init\rangle$$

Goal: Find a marked  $g$



$$\mathbf{W} = \text{Refl}(init) = 2|init\rangle\langle init| - \text{Id}$$

$$\mathbf{W} = \text{real unitary}$$

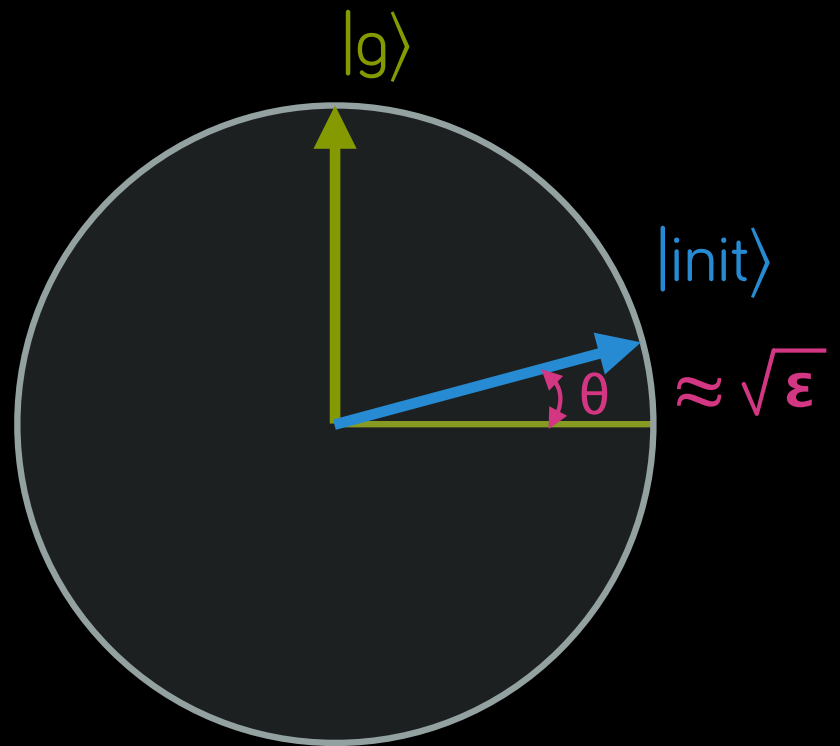
$$\text{Refl}(g) = \text{Id} - 2|g\rangle\langle g|$$

$$\text{Refl}(g) = \text{Id} - 2 \sum_{g \text{ marked}} |g\rangle\langle g|$$

# Two one-dimensional reflections

— **G** — **W** — Find a marked  $g$

1-dim **G** m-dim **G**  
 1-dim **W** now  
 Real **W**



$$\mathbf{G} = \text{Id} - 2|g\rangle\langle g|$$

$$\mathbf{W} = 2|\text{init}\rangle\langle \text{init}| - \text{Id}$$

$$\text{Refl}(\text{init}) \circ \text{Refl}(g) = \text{Rot}(2\theta)$$

$$[\text{Refl}(\text{init}) \circ \text{Refl}(g)]^{\sqrt{1/\epsilon}} |\text{init}\rangle \approx |g\rangle$$

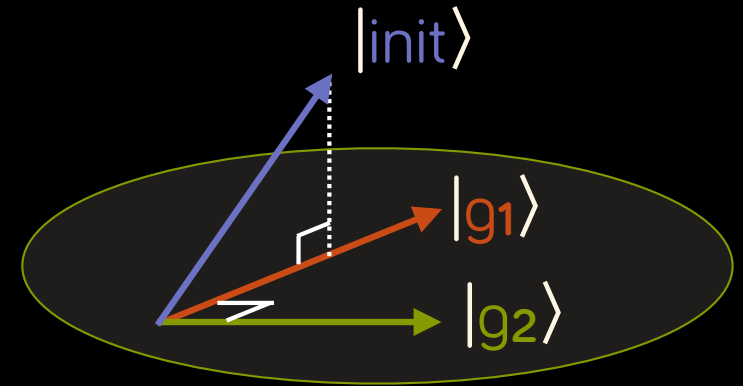
$$\langle g | \text{init} \rangle = \sin(\theta) \approx \sqrt{\epsilon}$$

$$\text{Cost}(\text{Rotate } |\text{init}\rangle \text{ by } 90^\circ) = \mathbf{S} + \sqrt{1/\epsilon} (\mathbf{C} + \mathbf{U})$$

# Multiple solutions

— **G** — **W** — Find a marked  $g$

1-dim <b>W</b>	1-dim <b>G</b>	m-dim <b>G</b>
Real <b>W</b>	2D rot	now



$$\text{Ref}(g) = \text{Id} - 2 \sum_{g \text{ marked}} |g\rangle\langle g|$$

$$\mathbf{W} = 2|\text{init}\rangle\langle \text{init}| - \text{Id}$$

$$\text{Let } |g_1\rangle = \sum_{g \text{ marked}} |g\rangle\langle g| |\text{init}\rangle, \text{ normalized}$$

$$\text{Let } |g_2\rangle \perp |g_1\rangle \quad \text{So, } \mathbf{G} |g_2\rangle = - |g_2\rangle$$

$$\text{Then } |g_2\rangle \perp |\text{init}\rangle \quad \text{So, } \mathbf{W} |g_2\rangle = - |g_2\rangle$$

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$$\mathbf{W}\mathbf{G} |g_2\rangle = |g_2\rangle$$

$$\mathbf{W}\mathbf{G} \text{ rotates in } \{ |\text{init}\rangle, |g_1\rangle \}$$


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# General W with unique solution

—  $\boxed{\mathbf{G}}$  —  $\boxed{\mathbf{W}}$  — Find a marked  $g$

$$\text{Refl}(g) = \text{Id} - 2|g\rangle\langle g|$$

W real-valued

$$W |init\rangle = |init\rangle$$

$$W |init^\perp\rangle \neq |init^\perp\rangle$$

1-dim  $\mathbf{W}$

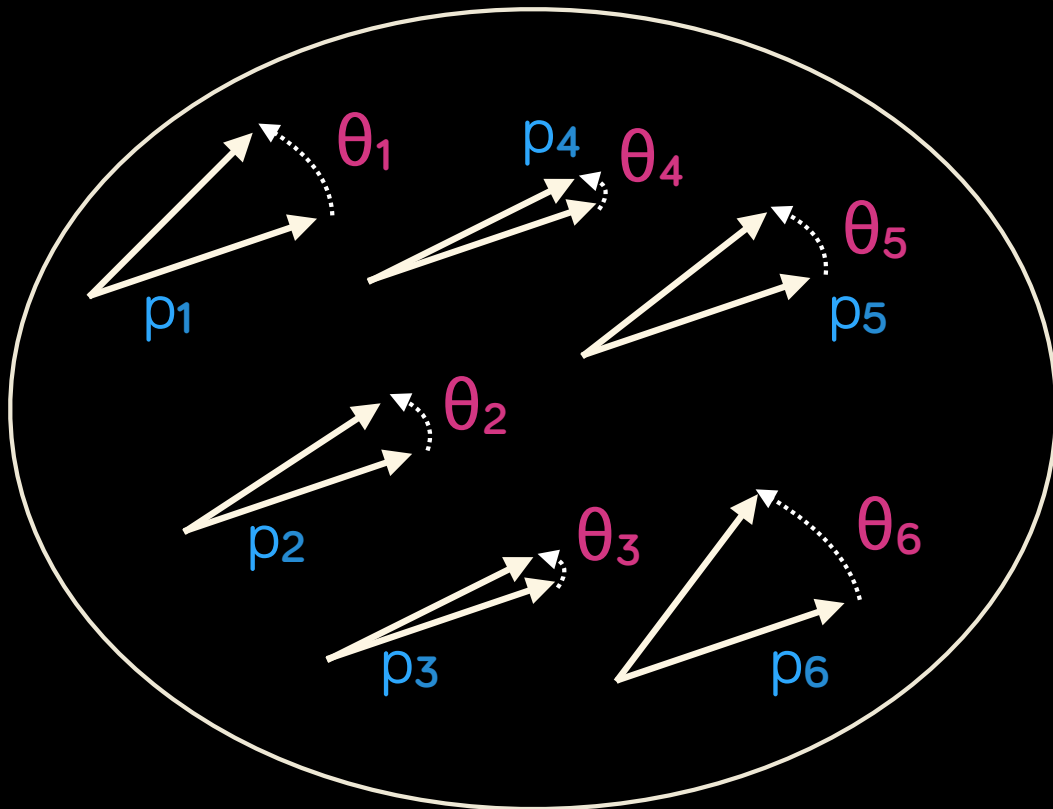
Real  $\mathbf{W}$

1-dim  $\mathbf{G}$  m-dim  $\mathbf{G}$

2D rot

2D rot

now



$$\sqrt{\frac{p_1}{\theta_1^2} + \frac{p_2}{\theta_2^2} + \frac{p_3}{\theta_3^2} + \frac{p_4}{\theta_4^2} + \frac{p_5}{\theta_5^2} + \frac{p_6}{\theta_6^2}}$$

$$= \text{Cost}(\text{Rotate } |init\rangle \text{ by } 90^\circ)$$

$$= \text{Cost}(\text{Phase estimation})$$

$$= \text{QHT}(W \circ \text{Refl}(g), |init\rangle)$$

$$= \sqrt{HT} = \sqrt{\text{Hitting Time}}$$

$$[W \circ \text{Refl}(g)]^{\sqrt{HT}} |init\rangle \begin{cases} \neq |init\rangle \\ \neq |g\rangle \end{cases}$$

# General W with unique solution

W real-valued

W  $|init\rangle = |init\rangle$

W  $|init^\perp\rangle \neq |init^\perp\rangle$

$$W = \begin{bmatrix} +1 & & & \\ & \varphi_1 & & \\ & & \varphi_2 & \\ & & & \varphi_3 \\ & & & & \varphi_4 \end{bmatrix}$$

$$\text{Refl}(init) = \begin{bmatrix} +1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \\ & & & & -1 \end{bmatrix}$$

$$\text{Cost} \approx \mathbf{S} + \sqrt{HT} (\mathbf{C} + \mathbf{U})$$

$$\text{Cost} \approx \mathbf{S} + \sqrt{1/\epsilon} (\mathbf{C} + \mathbf{U})$$

$$W^E = \begin{bmatrix} +1 & & & \\ & E\varphi_1 & & \\ & & E\varphi_2 & \\ & & & E\varphi_3 \\ & & & & E\varphi_4 \end{bmatrix} \not\approx \begin{bmatrix} +1 & & & \\ & -1 & & \\ & & -1 & \\ & & & -1 \\ & & & & -1 \end{bmatrix} = \text{Refl}(init)$$

$$[W^E \circ \text{Refl}(g)]^{\sqrt{1/\epsilon}} |init\rangle \not\approx |g\rangle$$

$$\text{Cost} \approx \mathbf{S} + \sqrt{1/\epsilon} \mathbf{C} + \sqrt{1/\epsilon} \mathbf{E} \mathbf{U}$$

# General $W$ with unique solution

Thm:  $W^E |g\rangle \approx |g^\perp\rangle$  for  $E = \sqrt{\varepsilon * HT}$   
 $W^E |init\rangle = |init\rangle$   

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 $W^E = \widetilde{\text{Refl}}(init)$  by using phase estimation

Cor:  $[\widetilde{\text{Refl}}(init) \circ \text{Refl}(g)]^{\sqrt{1/\varepsilon}} |init\rangle \not\approx |g\rangle$

$[W^E \circ \text{Refl}(g)]^{\sqrt{1/\varepsilon}} |init\rangle \not\approx |g\rangle$

Cost  $\approx S + \sqrt{1/\varepsilon} C + \sqrt{1/\varepsilon} EU$

# General W with unique solution

$$[\widetilde{\text{Refl}}(\text{init}) \circ \text{Refl}(g)]^{\sqrt{1/\epsilon}} |\text{init}\rangle \not\approx |g\rangle$$

$$\begin{array}{cccccccccccccccccccc}
 W & G & W & G & W & G & W & G & W & G & W & G & W & G & W & G & W & G & W & G \\
 \left( (W & G) W (G & W) G (W & G) \right) W \left( (G & W) G (W & G) W (G & W) \right) G \left( (W & G) W (G & W) G (W & G) \right)
 \end{array}$$

Recursive form:  $U U^{-1} U$

Do recursively:  $[\widetilde{\text{Refl}}(\text{init}) \circ \text{Refl}(g)]^{\sqrt{1/\epsilon}} |\text{init}\rangle \approx |g\rangle$

$$\text{Cost} \approx S + \sqrt{1/\epsilon} C + \sqrt{HT} U$$



# Overview

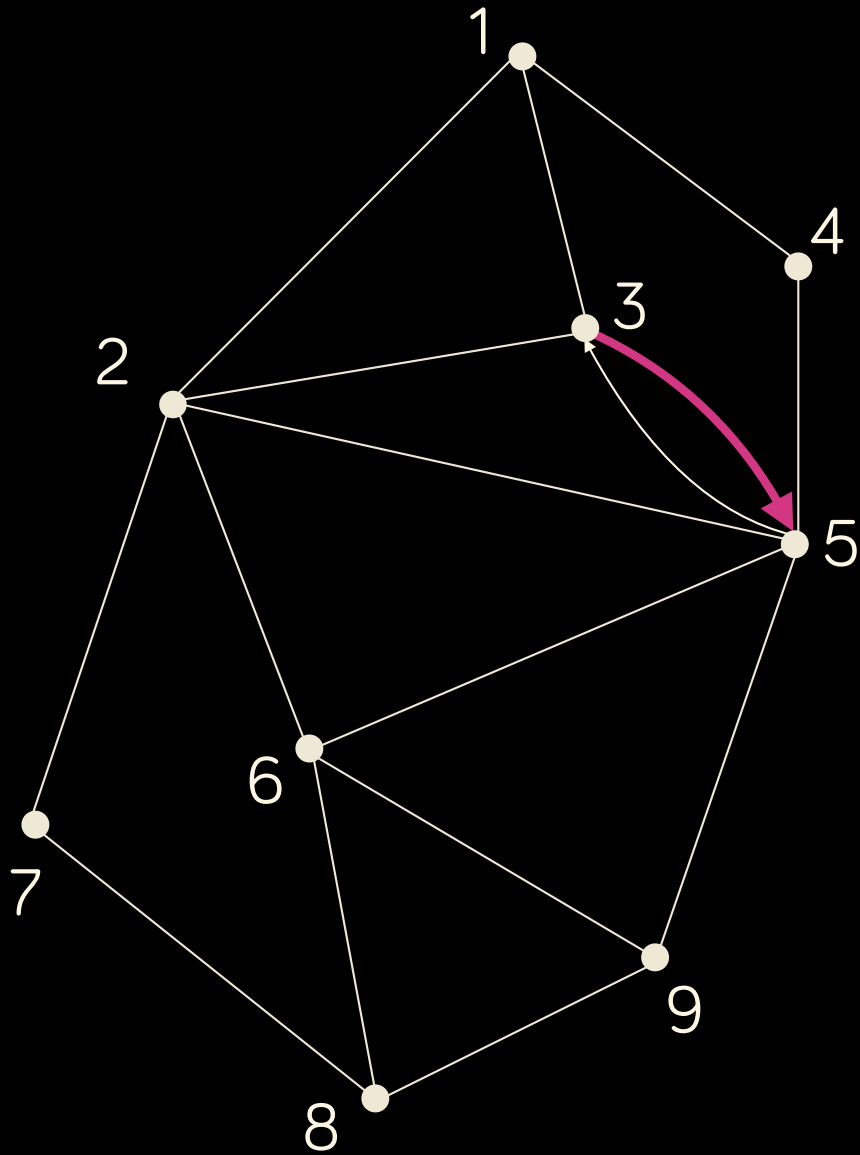
$$|\text{init}\rangle \text{---} \boxed{\text{G}} \text{---} \boxed{\text{W}} \text{---} |\text{final}\rangle \approx |g\rangle$$

	1-dim <b>G</b>	m-dim <b>G</b>
1-dim <b>W</b>	2D rot	2D rot
Real <b>W</b>	Rec. Ampl. Ampl	Mostly open

$$\text{Cost}(1\text{-dim } \mathbf{W}) \approx \mathbf{S} + \sqrt{1/\epsilon} (\mathbf{C} + \mathbf{U})$$

$$\text{Cost}(\text{real } \mathbf{W}) \approx \mathbf{S} + \sqrt{1/\epsilon} \mathbf{C} + \sqrt{HT} \mathbf{U}$$

# Random walk

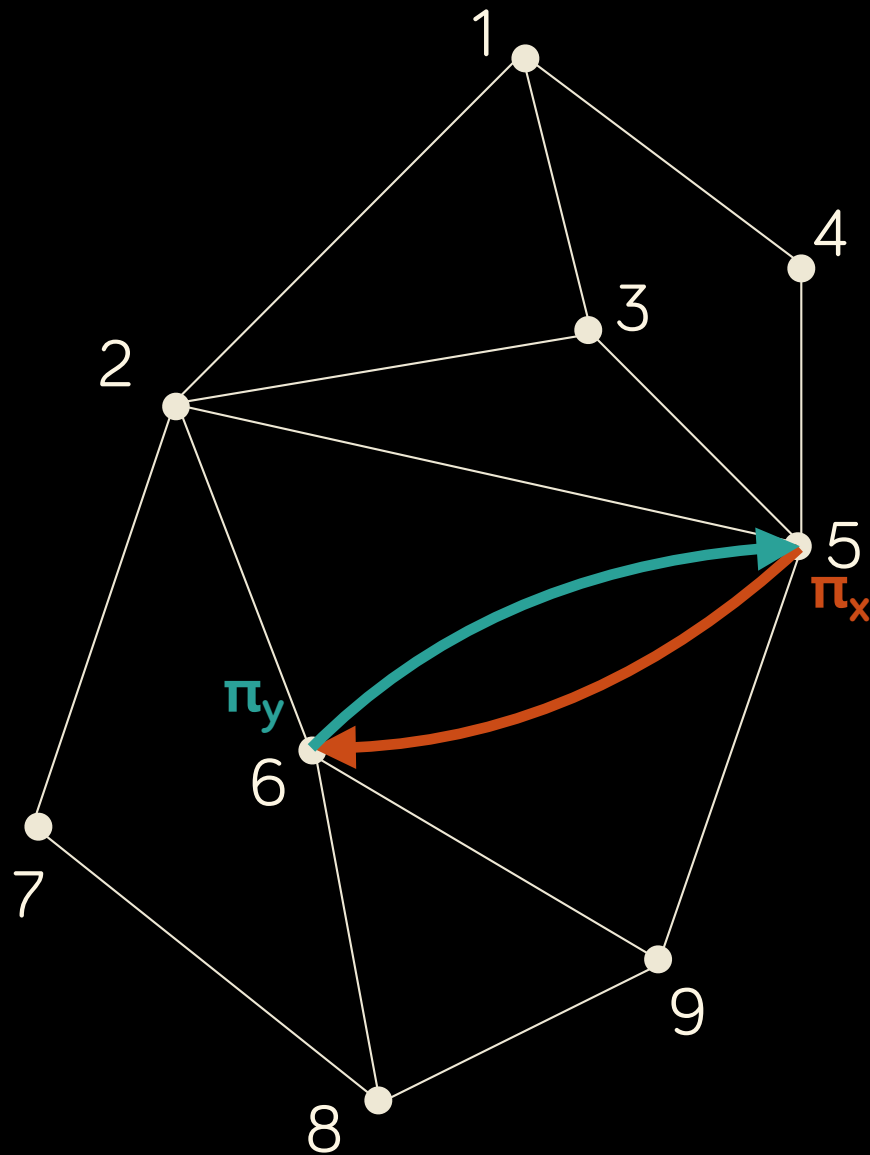


Probability to transit  
from 3 to 5 =  $p_{5 \leftarrow 3}$

$P =$

	1/5	1/3	1/2					
1/3		1/3		1/5	1/4	1/2		
1/3	1/5			1/5				
1/3				1/5				
	1/5	1/3	1/2		1/4			1/3
	1/5			1/5			1/3	1/3
	1/5						1/3	
					1/4	1/2		1/3
				1/5	1/4		1/3	

# Random walk



Columns sum to 1

Connected

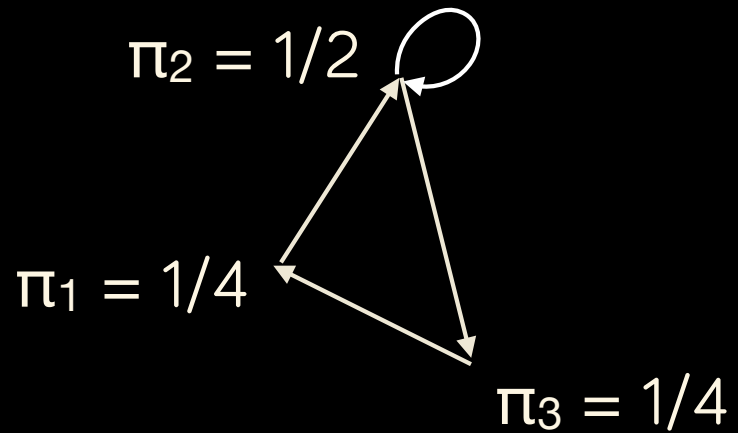
Stationary distr:  $P \vec{\pi} = \vec{\pi}$

Reversible:  $p_{y \leftarrow x} \pi_x = p_{x \leftarrow y} \pi_y$

$P =$

.1	.2	.1		.2	.2		.1	
.3		.2	.1		.3		.2	
.2			.4					.1
.4	.3			.3	.3	.1		.6
	.1	.6			.3			.1
	.2		.2	.4				.1
	.2		.3		.2		.4	
		.1				.9	.2	
				.1			.1	.1

# A non-reversible graph



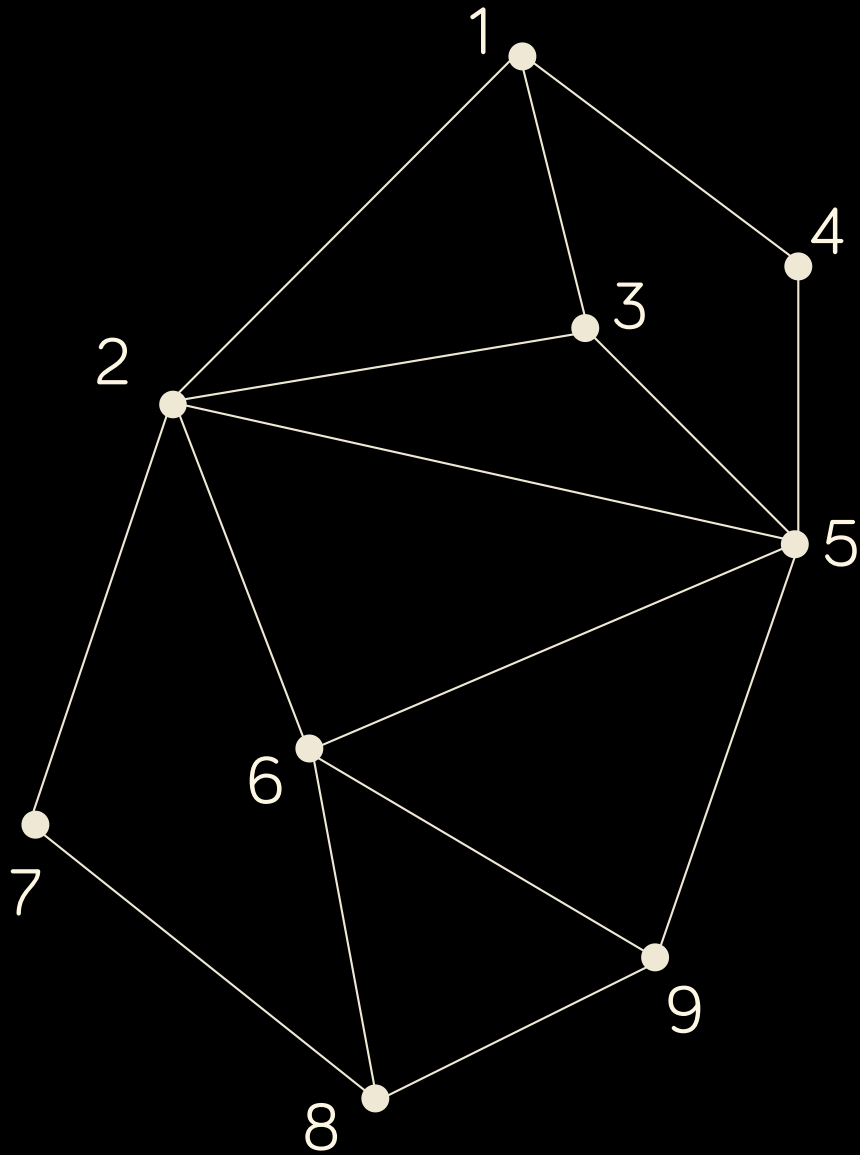
Columns sum to 1

Connected

Stationary distr.:  $P \vec{\pi} = \vec{\pi}$

Reversible:  $p_{y \leftarrow x} \pi_x \neq p_{x \leftarrow y} \pi_y$

# Random walk



Columns sum to 1

Connected

Stationary distr:  $P \vec{\pi} = \vec{\pi}$

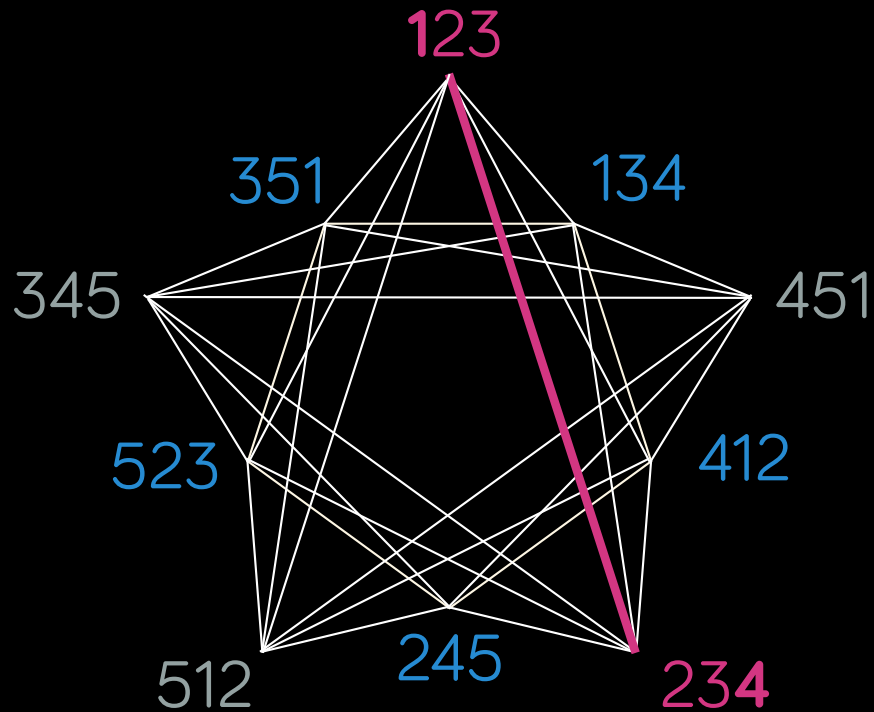
Reversible:  $p_{y \leftarrow x} \pi_x = p_{x \leftarrow y} \pi_y$

$\varepsilon = \text{Prob} [\text{random vertex is marked when picked from } \vec{\pi}]$

$P =$

	1/5	1/3	1/2					
1/3		1/3		1/5	1/4	1/2		
1/3	1/5			1/5				
1/3				1/5				
	1/5	1/3	1/2		1/4			1/3
	1/5			1/5			1/3	1/3
	1/5						1/3	
					1/4	1/2		1/3
				1/5	1/4		1/3	

# Hitting time



Complete graph

2D Grid

3D Grid

[N choose k]  
(Johnson graph)

Unique marked vertex

Hitting Time  $\epsilon$

$1/\epsilon$   $1/N$

$1/\epsilon \cdot \log(N)$   $1/N$

$1/\epsilon$   $1/N$

$1/\epsilon \cdot k$   $(k/N)^2$

$k = \text{poly}(N)$

for our applications

Vertex = Subset of size  $k$  out of  $[N] = \{1, 2, \dots, N\}$

Edge = Two subsets differ in one element

# Random walk

$$P = \begin{array}{|c|c|c|c|c|} \hline .1 & .2 & .2 & .3 & .3 \\ \hline .4 & .3 & .1 & 0 & 0 \\ \hline 0 & .1 & .1 & .7 & .4 \\ \hline 0 & .2 & .4 & 0 & .2 \\ \hline .5 & .2 & .2 & 0 & .1 \\ \hline \end{array}$$

Columns sum to 1

Connected

Stationary distr.:  $P \vec{\pi} = \vec{\pi}$

Reversible:  $p_{y \leftarrow x} \pi_x = p_{x \leftarrow y} \pi_y$

$$\sqrt{\pi} = \begin{array}{|c|c|} \hline \sqrt{\pi_1} & 0 \\ \hline & \sqrt{\pi_2} \\ \hline & & \ddots \\ \hline 0 & & & \sqrt{\pi_N} \\ \hline \end{array}$$

$$D(P) = \sqrt{P^T \circ P} = \sqrt{1/\pi} P \sqrt{\pi}$$

$$D(P)_{y \leftarrow x} = \sqrt{p_{y \leftarrow x} p_{x \leftarrow y}} = \langle y | p_x \rangle \langle x | p_y \rangle = \langle y, p_y | p_x, x \rangle = \langle y, p_y | S | x, p_x \rangle = \langle y | T^\dagger S T | x \rangle$$

$$\begin{aligned} (P^3)_{y \leftarrow x} &= ((\sqrt{\pi} D(P) \sqrt{1/\pi})^3)_{y \leftarrow x} = \langle y | \sqrt{\pi} T^\dagger S T T^\dagger S T T^\dagger S T \sqrt{1/\pi} | x \rangle \\ &= \langle y | \sqrt{\pi} T^\dagger S T T^\dagger S T T^\dagger S T \sqrt{1/\pi} | x \rangle = \sqrt{\pi_y} \langle y, p_y | (S T T^\dagger)^3 | x, p_x \rangle \sqrt{1/\pi_x} \end{aligned}$$

$$|p_x\rangle = \sum \sqrt{p_{y \leftarrow x}} |y\rangle$$

$$T |x\rangle = |x, p_x\rangle$$

$$T T^\dagger = \sum |x, p_x\rangle \langle x, p_x|$$

$$S = \text{Swap} = \sum |x, y\rangle \langle y, x|$$

$$T = \sum |x, p_x\rangle \langle x|$$

$$T^\dagger T = \text{Id}$$

# Quantum walk

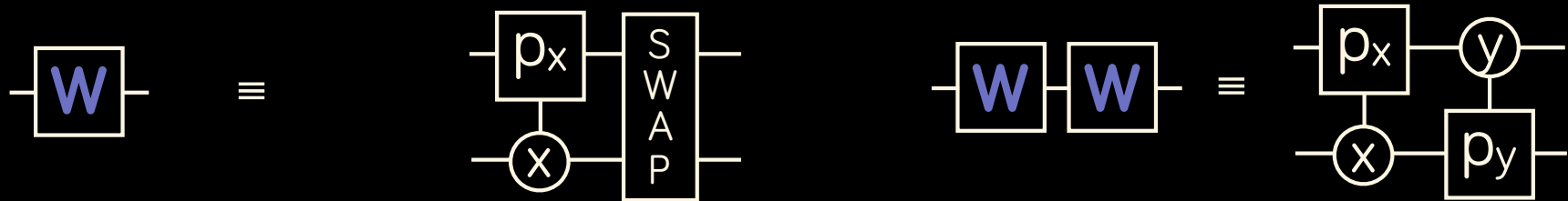
Stationary distr.:  $P \vec{\pi} = \vec{\pi}$

$$D(P) = \sqrt{P^T \circ P} = \sqrt{1/\pi} P \sqrt{\pi}$$

Reversible:  $\rho_{y \leftarrow x} \pi_x = \rho_{x \leftarrow y} \pi_y$

$$D(P)_{y \leftarrow x} = \langle y, \rho_y | \mathbf{S} \mathbf{T} \mathbf{T}^\dagger | x, \rho_x \rangle = \langle y | \mathbf{T}^\dagger \mathbf{S} \mathbf{T} | x \rangle$$

$$W(P) = \mathbf{S}(2\mathbf{T}\mathbf{T}^\dagger - \text{Id})$$



$$|p_x\rangle = \sum \sqrt{\rho_{y \leftarrow x}} |y\rangle$$

$$\mathbf{T} |x\rangle = |x, p_x\rangle$$

$$\mathbf{T} \mathbf{T}^\dagger = \sum |x, p_x\rangle \langle x, p_x|$$

$$\mathbf{S} = \text{Swap} = \sum |x, y\rangle \langle y, x|$$

$$\mathbf{T} = \sum |x, p_x\rangle \langle x|$$

$$\mathbf{T}^\dagger \mathbf{T} = \text{Id}$$



# Quantum walk

Stationary distr.:  $P \vec{\pi} = \vec{\pi}$

$$D(P) = \sqrt{P^T \circ P} = \sqrt{1/\pi} P \sqrt{\pi}$$

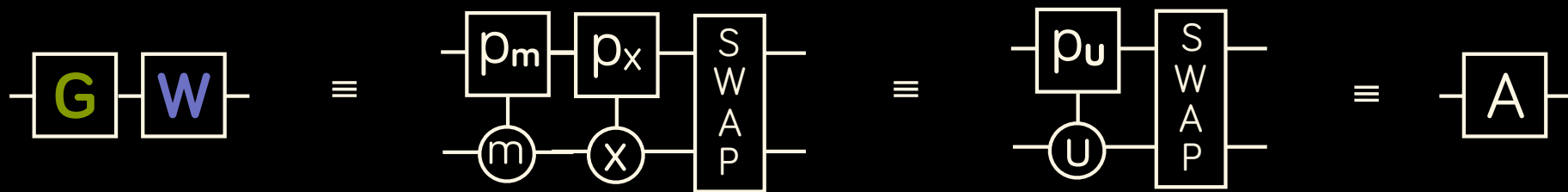
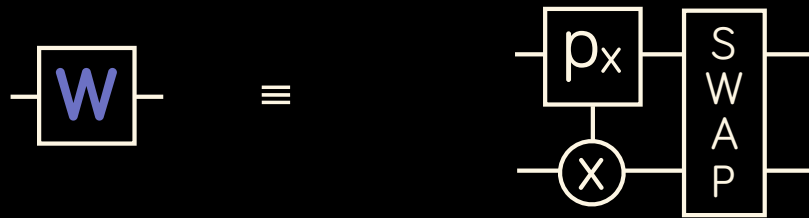
Reversible:  $\rho_{y \leftarrow x} \pi_x = \rho_{x \leftarrow y} \pi_y$

$$D(P)_{y \leftarrow x} = \langle y, p_y | \mathbf{S} \mathbf{T} \mathbf{T}^\dagger | x, p_x \rangle = \langle y | \mathbf{T}^\dagger \mathbf{S} \mathbf{T} | x \rangle$$

$$\mathbf{W}(P) = \mathbf{S}(2\mathbf{T}\mathbf{T}^\dagger - \text{Id})$$

$$| \text{final} \rangle = (\mathbf{W}\mathbf{G})^T | \text{init} \rangle$$

$$\mathbf{A} = \mathbf{W}\mathbf{G}$$



$$|p_x\rangle = \sum \sqrt{p_{y \leftarrow x}} |y\rangle$$

$$\mathbf{T} |x\rangle = |x, p_x\rangle$$

$$\mathbf{T}\mathbf{T}^\dagger = \sum |x, p_x\rangle \langle x, p_x|$$

$$\mathbf{S} = \text{Swap} = \sum |x, y\rangle \langle y, x|$$

$$\mathbf{T} = \sum |x, p_x\rangle \langle x|$$

$$\mathbf{T}^\dagger \mathbf{T} = \text{Id}$$

# Quantum walk

Stationary distr.:  $P \vec{\pi} = \vec{\pi}$

Reversible:  $\rho_{y \leftarrow x} \pi_x = \rho_{x \leftarrow y} \pi_y$

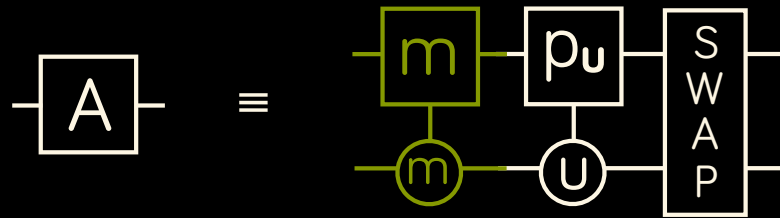
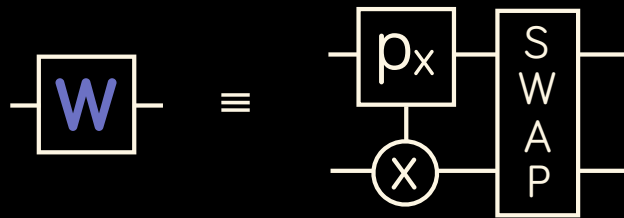
$$D(P') = \sqrt{P'^T \circ P'} = \sqrt{1/\pi} P' \sqrt{\pi}$$

$$D(P')_{y \leftarrow x} = \langle y, \rho_y | \mathbf{S} \mathbf{T} \mathbf{T}^\dagger | x, \rho_x \rangle = \langle y | \mathbf{T}^\dagger \mathbf{S} \mathbf{T} | x \rangle$$

$$W(P) = \mathbf{S}(2\mathbf{T}\mathbf{T}^\dagger - \text{Id})$$

$$A = W(P') = \mathbf{S}(2\mathbf{T}\mathbf{T}^\dagger - \text{Id})$$

$$A = \mathbf{W}\mathbf{G}$$



$$P =$$

.1	.2	.2	.3	.3
.4	.3	.1	0	0
0	.1	.1	.7	.4
0	.2	.4	0	.2
.5	.2	.2	0	.1

$$P' =$$

.1	.2	.2	0	0
.4	.3	.1	0	0
0	.1	.1	0	0
0	.2	.4	1	0
.5	.2	.2	0	1

Marked = {4, 5}

$$|p_x\rangle = \sum \sqrt{\rho_{y \leftarrow x}} |y\rangle$$

$$\mathbf{T} |x\rangle = |x, p_x\rangle$$

$$\mathbf{T}\mathbf{T}^\dagger = \sum |x, p_x\rangle\langle x, p_x|$$

$$\mathbf{S} = \text{Swap} = \sum |x, y\rangle\langle y, x|$$

$$\mathbf{T} = \sum |x, p_x\rangle\langle x|$$

$$\mathbf{T}^\dagger\mathbf{T} = \text{Id}$$

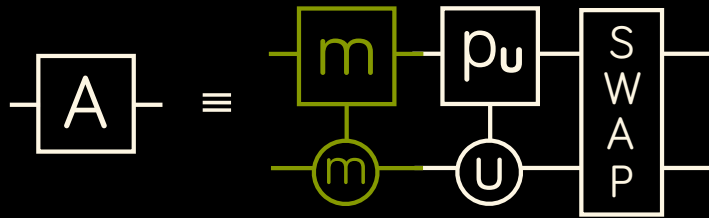
$$\mathbf{T} = \sum |u, p_u\rangle\langle u| + \sum |m, m\rangle\langle m|$$

# Quantum walk

$$D(P')_{y \leftarrow x} = \langle y | T^\dagger S T | x \rangle$$

$$= \langle y, p_y | S T T^\dagger | x, p_x \rangle$$

$$A = W(P') = S(2TT^\dagger - \text{Id})$$



$$D(P') = \begin{bmatrix} .1 & .3 & .1 & 0 & 0 \\ .3 & .2 & .1 & 0 & 0 \\ .1 & .1 & .1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T = \sum |u, p_u \rangle \langle u| + \sum |m, m \rangle \langle m|$$

## Spectra of $D(P')$ and $W(P')$ :

Pick  $T^\dagger S T \vec{\lambda}_D = \lambda \vec{\lambda}_D \quad (\lambda < 1)$

Consider  $|\lambda\rangle = T \vec{\lambda}_D$

$$W(P')|\lambda\rangle$$

$$= S(2TT^\dagger - \text{Id})|\lambda\rangle$$

$$= 2STT^\dagger|\lambda\rangle - S|\lambda\rangle$$

$$= 2STT^\dagger T \vec{\lambda}_D - S|\lambda\rangle$$

$$= 2ST \vec{\lambda}_D - S|\lambda\rangle$$

$$= 2S|\lambda\rangle - S|\lambda\rangle$$

$$= S|\lambda\rangle$$

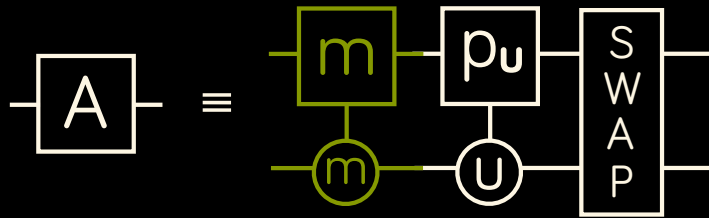
$$T = \sum |u, p_u \rangle \langle u| + \sum |m, m \rangle \langle m|$$

# Quantum walk

$$D(P')_{y \leftarrow x} = \langle y | T^\dagger S T | x \rangle$$

$$= \langle y, p_y | S T T^\dagger | x, p_x \rangle$$

$$A = W(P') = S(2TT^\dagger - \text{Id})$$



$$D(P') = \begin{bmatrix} .1 & .3 & .1 & 0 & 0 \\ .3 & .2 & .1 & 0 & 0 \\ .1 & .1 & .1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T = \sum |u, p_u\rangle \langle u| + \sum |m, m\rangle \langle m|$$

## Spectra of $D(P')$ and $W(P')$ :

Pick  $T^\dagger S T \vec{\lambda}_D = \lambda \vec{\lambda}_D$  ( $\lambda < 1$ )

Consider  $|\lambda\rangle = T \vec{\lambda}_D$

$$W(P')|\lambda\rangle = S|\lambda\rangle$$

$$W(P') S|\lambda\rangle$$

$$= S(2TT^\dagger - \text{Id}) S|\lambda\rangle$$

$$= 2 S T T^\dagger S|\lambda\rangle - |\lambda\rangle$$

$$= 2 S T T^\dagger S T \vec{\lambda}_D - |\lambda\rangle$$

$$= 2 \lambda S T \vec{\lambda}_D - |\lambda\rangle$$

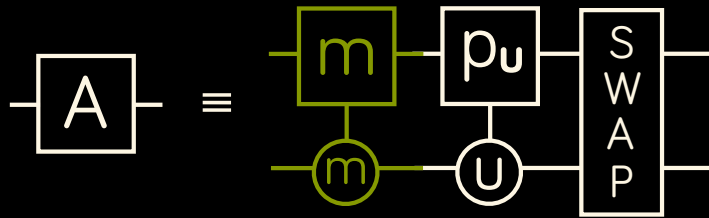
$$= 2 \lambda S|\lambda\rangle - |\lambda\rangle$$

# Quantum walk

$$D(P')_{y \leftarrow x} = \langle y | T^\dagger S T | x \rangle$$

$$= \langle y, p_y | S T T^\dagger | x, p_x \rangle$$

$$A = W(P') = S(2TT^\dagger - \text{Id})$$



$$D(P') = \begin{bmatrix} .1 & .3 & .1 & 0 & 0 \\ .3 & .2 & .1 & 0 & 0 \\ .1 & .1 & .1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T = \sum |u, p_u\rangle \langle u| + \sum |m, m\rangle \langle m|$$

## Spectra of $D(P')$ and $W(P')$ :

Pick  $T^\dagger S T \vec{\lambda}_D = \lambda \vec{\lambda}_D \quad (\lambda < 1)$

Consider  $|\lambda\rangle = T \vec{\lambda}_D$

$$W(P')|\lambda\rangle = S|\lambda\rangle$$

$$W(P') S|\lambda\rangle = 2\lambda S|\lambda\rangle - |\lambda\rangle$$

$W(P')$  rotates 2D-subspace

$$\{ |\lambda\rangle, S|\lambda\rangle \}$$

by angle

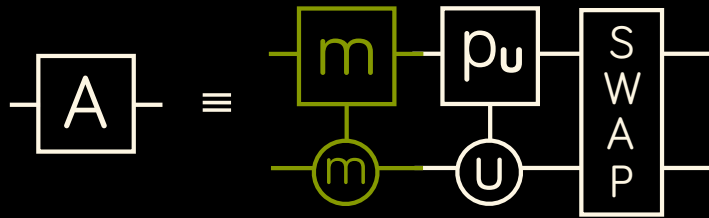
$$\langle \lambda | S|\lambda \rangle = \lambda = \cos(\Theta)$$

# Quantum walk

$$D(P')_{y \leftarrow x} = \langle y | T^\dagger S T | x \rangle$$

$$= \langle y, p_y | S T T^\dagger | x, p_x \rangle$$

$$A = W(P') = S(2TT^\dagger - Id)$$



$$D(P') = \begin{bmatrix} .1 & .3 & .1 & 0 & 0 \\ .3 & .2 & .1 & 0 & 0 \\ .1 & .1 & .1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$T = \sum |u, p_u \rangle \langle u| + \sum |m, m \rangle \langle m|$$

## Hitting Time of $D(P')$ and $W(P')$ :

Expected #steps to reach a marked vertex, starting from the stationary distr.  $\vec{\pi}$

$D(P')$					$\sqrt{\vec{\pi}}$	
$\vec{\lambda}_D$			0	0	$b_1$	
			0	0	$b_2$	
			0	0	$b_3$	
0	0	0	1	0	0	
0	0	0	0	1	0	

$$P' = \sqrt{\vec{\pi}} D(P') \sqrt{1/\vec{\pi}}$$

$$\sqrt{\vec{\pi}} = b_1 \vec{\lambda}_{D1} + b_2 \vec{\lambda}_{D2} + b_3 \vec{\lambda}_{D3}$$

$$HT = \sum_j \frac{b_j^2}{1 - \lambda_{Dj}}$$

# Quantum walk

$$\text{QHT} = \sqrt{\sum \frac{\text{Probability}}{\text{phase}^2}}$$

## Hitting Time of $D(P')$ and $W(P')$ :

Expected #steps to reach a marked vertex, starting from the stationary distr.  $\vec{\pi}$

$W(P')$  rotates  $|\lambda_1\rangle$  by angle  $\theta_1 \approx \sqrt{1 - \lambda_1}$   
since  $\lambda_1 = \cos(\theta_1)$

$$|\text{init}\rangle = b_1|\lambda_1\rangle + b_2|\lambda_2\rangle + b_3|\lambda_3\rangle$$

$$\text{QHT} = \sqrt{\sum_j \frac{b_j^2}{1 - \lambda_{Dj}}}$$

# Quantum walk

Stationary distr.:  $P \vec{\pi} = \vec{\pi}$

Reversible:  $\rho_{y \leftarrow x} \pi_x = \rho_{x \leftarrow y} \pi_y$

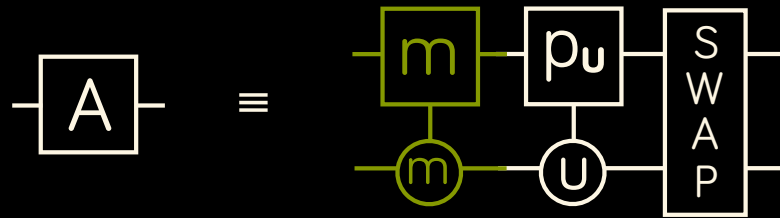
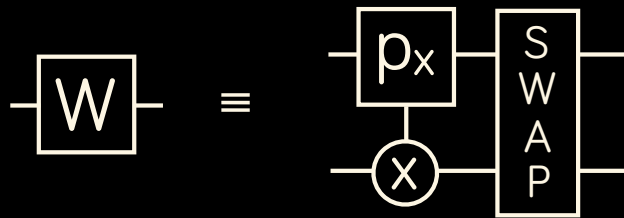
$$D(P') = \sqrt{P'^T \circ P'} = \sqrt{1/\pi} P' \sqrt{\pi}$$

$$D(P')_{y \leftarrow x} = \langle y, \rho_y | \mathbf{S} \mathbf{T} \mathbf{T}^\dagger | x, \rho_x \rangle = \langle y | \mathbf{T}^\dagger \mathbf{S} \mathbf{T} | x \rangle$$

$$W(P) = \mathbf{S}(2\mathbf{T}\mathbf{T}^\dagger - \text{Id})$$

$$A = W(P') = \mathbf{S}(2\mathbf{T}\mathbf{T}^\dagger - \text{Id})$$

$$A = \mathbf{W}\mathbf{G}$$



$$P =$$

.1	.2	.2	.3	.3
.4	.3	.1	0	0
0	.1	.1	.7	.4
0	.2	.4	0	.2
.5	.2	.2	0	.1

$$P' =$$

.1	.2	.2	0	0
.4	.3	.1	0	0
0	.1	.1	0	0
0	.2	.4	1	0
.5	.2	.2	0	1

Marked = {4, 5}

$$|p_x\rangle = \sum \sqrt{\rho_{y \leftarrow x}} |y\rangle$$

$$\mathbf{T} |x\rangle = |x, p_x\rangle$$

$$\mathbf{T} \mathbf{T}^\dagger = \sum |x, p_x\rangle \langle x, p_x|$$

$$\mathbf{S} = \text{Swap} = \sum |x, y\rangle \langle y, x|$$

$$\mathbf{T} = \sum |x, p_x\rangle \langle x|$$

$$\mathbf{T}^\dagger \mathbf{T} = \text{Id}$$

$$\mathbf{T} = \sum |u, p_u\rangle \langle u| + \sum |m, m\rangle \langle m|$$



# Quantum walk

Stationary distr.:  $P \vec{\pi} = \vec{\pi}$

$$D(P) = \sqrt{P^T \circ P} = \sqrt{1/\pi} P \sqrt{\pi}$$

Reversible:  $\rho_{y \leftarrow x} \pi_x = \rho_{x \leftarrow y} \pi_y$

$$D(P)_{y \leftarrow x} = \langle y, \rho_y | \mathbf{S} \mathbf{T} \mathbf{T}^\dagger | x, \rho_x \rangle = \langle y | \mathbf{T}^\dagger \mathbf{S} \mathbf{T} | x \rangle$$

$$W(P) = \mathbf{S}(2\mathbf{T}\mathbf{T}^\dagger - \text{Id})$$

$$1. W(P) |\text{init}\rangle = |\text{init}\rangle \quad \text{for } |\text{init}\rangle = \mathbf{T} \sqrt{1/\pi} \vec{\pi} = \sum \sqrt{\pi_x} |x, \rho_x\rangle$$

$$\mathbf{S} |\text{init}\rangle = |\text{init}\rangle$$

$$2. W(P) \text{ acts on } \{|x, \rho_x\rangle, \mathbf{S}|x, \rho_x\rangle\}$$

$$\text{Dim}(W) = 2 \text{ \#vertices} - 1$$

$W$  is a walk on the directed edges (not vertices)

$$|\rho_x\rangle = \sum \sqrt{\rho_{y \leftarrow x}} |y\rangle$$

$$\mathbf{T} |x\rangle = |x, \rho_x\rangle$$

$$\mathbf{T} \mathbf{T}^\dagger = \sum |x, \rho_x\rangle \langle x, \rho_x|$$

$$\mathbf{S} = \text{Swap} = \sum |x, y\rangle \langle y, x|$$

$$\mathbf{T} = \sum |x, \rho_x\rangle \langle x|$$

$$\mathbf{T}^\dagger \mathbf{T} = \text{Id}$$

# Element distinctness

12	6	7	2	14	10	9	7	20	5	1	16	17
----	---	---	---	----	----	---	---	----	---	---	----	----

$[N] = \{1, 2, \dots, N\}$

Algorithm:

Pick  $k$  indices  $K \subseteq [N]$

Query oracle on  $K$

Repeat

Check for collision in  $K$

Replace **one** index in  $K \subseteq [N]$

Query oracle on the new index

$$|\text{final}\rangle = (\mathbf{W}\mathbf{G})^T |\text{init}\rangle$$

Setup  $\mathbf{S} = k$

Check  $\mathbf{C} = 0$

Update  $\mathbf{U} = 1$

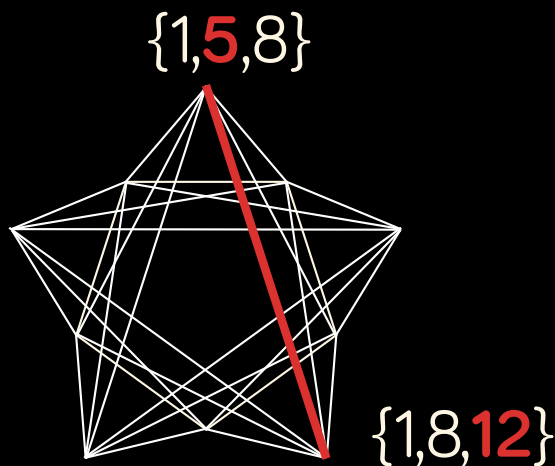
$$HT = \frac{N^2}{k}$$

$$\text{Cost} = \mathbf{S} + \sqrt{HT} (\mathbf{C} + \mathbf{U})$$

$$= k + \sqrt{N^2/k} (0 + 1)$$

$$= k + \sqrt{N^2/k}$$

$$= N^{2/3} \quad \text{for } k = N^{2/3}$$



# Non-Disjointness

$\{0\}$   $a \in \{0,1\}^N$

0 0 1 1 0 1 1 0 1 1 0 0

$\{0\}$

$b \in \{0,1\}^N$

0 1 0 0 1 0 0 0 0 1 0 1 1

$\exists$  index  $i: a_i = b_i = 1$  ?

$$\sum |i\rangle |0\rangle$$

$$\sum |i\rangle |a_i\rangle$$

$$\sum |i\rangle |a_i\rangle$$

$$\sum (-1)^{a_i \wedge b_i} |i\rangle |a_i\rangle$$

$$\sum (-1)^{a_i \wedge b_i} |i\rangle |a_i\rangle$$

$$\sum (-1)^{a_i \wedge b_i} |i\rangle |0\rangle$$

Bits sent

Trivial

N

Random

$N \log N$

Q Search

$\sqrt{N} \log N$

# Non-Disjointness

$\Omega$   $a \in \{0,1\}^N$

0	0	1	1	0
1	1	0	0	1
0	0	0	1	0
1	0	0	1	1
0	0	0	1	0

cell i

$\Omega$   $b \in \{0,1\}^N$

0	1	0	0	1
0	0	0	1	0
1	1	0	0	1
0	1	0	0	0
1	0	1	0	0

cell i

$\exists$  index i:  $a_i = b_i = 1$  ?

	Bits sent
Trivial	N
Random	$N \log N$
Q Search	$\sqrt{N} \log N$
2D-Grid	$N \log N$

my cell contains 1

picks next  $\in_R$   
 {left, above, right, below}

go to the left cell

Hitting Time on 2D-Grid  
 =  $N \log N$

# Non-Disjointness

$\Omega$   $a \in \{0,1\}^N$

0	0	1	1	0
1	1	0	0	1
0	0	0	1	0
1	0	0	1	1
0	0	0	1	0

$$\sum |i\rangle$$



$$\sum (-1)^{a_i \wedge b_i} |i\rangle$$

$\Omega$

$b \in \{0,1\}^N$

0	1	0	0	1
0	0	0	1	0
1	1	0	0	1
0	1	0	0	0
1	0	1	0	0

$$|i\rangle$$

$$|i\rangle$$

Non-Disjointness can be solved with  $\sqrt{N}$  qubits communicated

$\exists$  index  $i: a_i = b_i = 1$  ?

	Bits sent
Trivial	$N$
Random	$N \log N$
Q Search	$\sqrt{N} \log N$
2D-Grid	$N \log N$
Q 2D-Grid	$\sqrt{N \log N}$
3D-Grid	$N$
Q 3D-Grid	$\sqrt{N}$

Hitting Time on 3D-Grid  
=  $N$

# References

## Algorithmic basis

- Grover STOC'96
- Brassard, Høyer ISTCS'97
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## Optimality

- Ambainis JCSS'02
- Reichardt SODA'09
- Høyer, Lee, Špalek STOC'04

## Quantum walks

- Ambainis SICOMP'07
- Szegedy FOCS'04
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- Magniez, Nayak, Richter, Santha Algo.'12
- Krovi, Magniez, Ozols, Roland Algo.'15
- Dohotaru, Høyer ICALP'17

## Applications

- Aaronson, Ambainis ToC'05
- Ambainis SICOMP'07
- Le Gall FOCS'14

Quantum search  
Amplitude amplification  
Phase Estimation

Lower bound  
Upper bound

Correspondence  
State-transitive  
Interpolated  
Controlled Walks

Disjointness  
Elem. Distinctness  
Triangle finding

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Thank you